# AF Zoom Lens <br> Instruction Manual 

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LMZ1236AMPDC-XFAF LMZ0824AMPDC-XFAF LMZ1000AMPDC-XFAF LMZ20750AMPDC-XFAF LMZ20550AMPDC-IRAF LMZ11176AMPDC-IRAF LMZ25300AMPDC-IRAF LMZ10360AMPDC-IRAF LMZ14500AMPDC-IRAF LMZ16160AMPDC-IRAF

Kowa) Kowa Optical Products Co. Ltd.

## 1. Precautions

- Warning and caution labels

This instruction manual uses the following labels. Understand the meaning of the labels before reading the instructions.

Failure to follow the instructions on this label may lead to a fatal accident or serious injury.

## Caution

Improper handling of the product without following the instructions on this label may lead to personal injury or property damage.

- Understanding the pictorial indications

For safe use of this product, this manual uses pictures that represent warnings and cautions. Understand these pictorial indications before using the product.


The $\boldsymbol{\Delta}$ picture indicates that you should pay attention it.


The $\theta$ picture indicates that you MUST NOT do something.
For example, the left picture means "do not disassemble."

The $\bullet$ picture indicates that you MUST do something.
For example, the left picture indicates that you must remove the cable from the connector.

- In case any of the following irregularities occurs, stop using the product.
* Continuing to use the product causes a fire, electric shock, burn, or failure.
- An abnormal condition is encountered such as smoke and a strange smell.
- Water or a material has entered the product.
- The product has been dropped or become damaged.
- A cable is damaged (e.g., the core is exposed or broken).

In any of these cases, immediately turn off the product and disconnect the cables. Then, contact your distributor or KOWA OPTICAL PRODUCTS CO.,LTD. for repair.


Do not repair, disassemble, or alter the product.

* Doing so causes a fire, electric shock, burn, or failure.

- When the product must be connected to a different device, follow the instructions for that device to connect the product in the correct procedure.
* Failure to do so may cause an unexpected problem.

- Do not place the product on an unstable surface.
* Doing so may cause the product to drop or fall causing personal injury or a product failure.

- Do not connect the product in any manner not specified in this instruction manual.
* Doing so may cause a fire, electric shock, burn, or failure.

- Ensure that the cables are seated all the way in.
* Failure to do so may cause a short circuit, fire, electric shock, burn, or failure.

- Do not insert a object into the product.
* Doing so may cause a fire, electric shock, burn, and failure.
- Do not wet the product or use or store in wet locations.
* Doing so may cause a fire, electric shock, burn, and failure.
- Do not handle the product with wet hands.
* Doing so may cause a fire, electric shock, burn, and failure.
- When thunder is heard, disconnect the cables or turn off the device connected to the product.
* Failure to do so may cause a failure or electric shock.
- Do not keep any containers containing a liquid or small metal objects on or near the product.
* They may enter the product for some reason, causing a fire, electric shock, burn, or failure.
- For this product, use a UL-complaint power supply with a nominal output of 12V DC and a maximum rated short-circuit current of 2 A or a power supply bearing an LPS (Limited Power Source) label.
* Failure to do so may cause a failure or electric shock.


## Caution

- We will not be liable for any damage caused by loss or corruption of data saved on your computer during the use of the product. You must be responsible for backing up your data.
- Slowly insert or disconnect each cable into/from the corresponding connector straight and in the correct direction. Do not apply undue force or squeeze a cable into a connector.
* Doing so may cause a failure.

- Do not apply stress on cables or connectors.
* Doing so may cause a failure.
- Do not use or store the product at any of the following places.
* Doing so may cause a failure.
- Places exposed to high temperatures or high humidity beyond the specified temperature range or places with much dust
- Places near a heat source (e.g., stove and heater)
- Wet place
- Places exposed to significant temperature or humidity changes
- Places exposed to vibration and/or impact
- Places exposed to direct sunlight
- Do not drop the product or apply an impact to the product.
* Doing so may cause a failure.
- Do not place a heavy object on the product.
* Doing so may cause the product to lose its balance and drop or fall, leading to personal injury or a product failure.
- Do not connect or disconnect cables to/from the product without turning off the device connected with the product.
* Doing so may cause an electric shock or failure.
- Do not strongly hold down or strike cables or connectors or do not try to route them with undue force.
* Doing so may cause a failure or damage parts, leading to personal injury.
- When moving the product, ensure that the connected cables are removed.
* Moving the product with the cables connected may cause a fire, electric shock, or failure.
- When the product will not be used for long periods, disconnect the cables.
* Failure to do so may cause a fire or failure.

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- When disconnecting a cable, do not pull on the cable itself but hold the connector.
* Pulling the cable alone may cause it to be damaged, leading to a fire, electric shock, or failure.

- Do not use the product with condensation in it.
* Doing so may cause a fire, electric shock, or failure.

- Do not use a mobile phone or other devices that emit radio waves near the product.
* Doing so may cause the product to malfunction.
- To remove stains from the product, use a dry, soft cloth to wipe the product. To use detergent to remove stains, be sure to disconnect the cables and dilute the neutral detergent with water.
* Do not use a detergent that contains benzene, thinner, alcohol, or the like. Using such a detergent may discolor or deteriorate the product.


## 1. Scope

This document is the instruction manual for LMZ1236AMPDC-XFAF and LMZ1000AMPDC-XFAF.

## 2. Overview

The lens has 2 motors for zoom and focus, 2 potentiometers for zoom and focus, and control PCB. The lens performs one time AF by analogue video signal from the camera. The iris can be controlled by DC-IRIS. The lens supports PELCO-D controlling with RS422 or RS485.
3. Contents
-AF zoom lens 1

- lens cover 1
- C-mount cover 1
- This document 1

| Video input | Analogue video signal NTSC/PAL |
| :--- | :--- |
| Video output | Analogue video signal NTSC/PAL |
| Video connector | 2 BNC(in and out) |
| Lens mount | C-mount |
| Flange back | 17.526 mm |
| Power | DC $+12 \mathrm{~V} \pm 10 \%$ |
| Power consumption | 10 W |
| Operation temperature and <br> humidity | $-10-+50$ degrees Celsius / 20-80 \% (without condensation) |
| Storage temperature and |  |
| humidity | -20 degrees Celsius / 20-90 \% (without condensation) |
| IRIS control | 4pin DC-Iris |
| Control cable | CE (EN6100 <br> FCC part-15 class B <br> Supported standards <br> RoHS |
| Product life | Zoom: 100,000 round trip <br> Focus: 100,000 round trip or AF 50,000 times |

Table 1 specifications

## 5. Out drawing

The out drawing of the back panel is shown in Fig.1.


Fig. 1 Back panel out drawing
The DIPSW setting is shown in Table 2.

| No. |  | ON | OFF |
| :--- | :--- | :--- | :--- |
| DIPSW1 | RS422/485 Tx terminator switch | Enable | Disable |
| DIPSW2 | RS422 Rx terminator switch | Enable | Disable |

Table 2 DIPSW setting

The DIPSW1 and DIPSW2 default settings are OFF. The termination resistors are 110 ohm .

## 6. Connections

The connection diagram is shown below.


Fig. 2 Connection diagram

The cable assign of the 14 lines loos end cable is shown in Table 3.

| Color | Description | Note |
| :--- | :--- | :--- |
| Shield | Shield | Connect to the FG of the controller. |
| Blue | RS422 RXD- |  |
| Gray | RS422 RXD+ | The output of the zoom potentiometer. |
| Yellow | ROOM WIPER | 0-5V (Typ.) with 470 Ohm series resistor. |

Table 3 The cable assign of the 14 lines loos end cable
7. Control commands

The lens can be controlled by PELCO-D serial commands. The UART format is shown below.

| Baud rate | $2400 / 4800 / 9600($ default $) / 19200 / 38400$ |
| :--- | :--- |
| Data-bit | 8 bit |
| Parity | None |
| Stop bit | 1 bit |

Supported commands are shown in Table 4.

| Command | Description |
| :--- | :--- |
| Move Focus To Near | Moving to Near side. The motor stops by the stop command. |
| Move Focus To Far | Moving to Focus side. The motor stops by the stop command. |
| Move Zoom To Wide | Moving to Wide side. The motor stops by the stop command. |
| Move Zoom To Tele | Moving to Tele side. The motor stops by the stop command. |
| Stop | Stop the motor. |
| Execute AF | Executing AF one time. |
| Inquiry Focus position | Inquiring the focus position $(0 x 0000 \sim 0 x F F F F)$ |
| Inquiry Zoom position | Inquiring the zoom position $(0 x 0000 \sim 0 x F F F F)$ |
| Set Zoom position | Preset the zoom position (0x0000~0xFFFF) |
| Set Focus position | Preset the focus position (0x0000~0xFFFF) |
| Set Continuously Focus Speed | Set the zoom motor speed for each 4 levels |
| Set Continuously Zoom Speed | Set the focus motor speed for each 4 levels |
| Set Zoom Speed | Set the zoom motor speed(from 4 levels) |
| Set Focus Speed | Set the focus motor speed(from 4 levels) |

Table 4 Supported commands
The command structure is shown below.

| Sync Byte | Address | Command1 | Command2 | Data1 | Data2 | Checksum |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |

The Sync Byte (synchronization byte) is always 0xFF. The address is the logical address of the receiver/driver being controlled. The check sum is a 8-bits value calculated by modulo 256 of the payload data that consists of 5 bytes (from "Address" to "Data2"). After sending a command, you should basically wait for the reply from the lens.

## Move Focus to Near

| Synch Byte | Address | Command1 | Command2 | Data1 | Data2 | Checksum |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| FFh | ID | $\mathbf{0 1 h}$ | $\mathbf{0 0 h}$ | $\mathbf{0 0 h}$ | $\mathbf{0 0 h}$ | $00 h-\mathrm{FFh}$ |

reply

| Synch Byte | Address | Data | Checksum |
| :---: | :---: | :---: | :---: |
| FFh | ID | 00 h | $00 \mathrm{~h}-\mathrm{FFh}$ |

Move Focus to Far

| Synch Byte | Address | Command1 | Command2 | Data1 | Data2 | Checksum |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| FFh | ID | $\mathbf{0 0 h}$ | $\mathbf{8 0 h}$ | $\mathbf{0 0 h}$ | $\mathbf{0 0 h}$ | 00h-FFh |

reply

| Synch Byte | Address | Data | Checksum |
| :---: | :---: | :---: | :---: |
| FFh | ID | 00 h | $00 \mathrm{~h}-\mathrm{FFh}$ |

## Move Zoom to Wide

| Synch Byte | Address | Command1 | Command2 | Data1 | Data2 | Checksum |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| FFh | ID | $\mathbf{0 0 h}$ | $\mathbf{4 0 h}$ | $\mathbf{0 0 h}$ | $\mathbf{0 0 h}$ | 00h-FFh |

reply

| Synch Byte | Address | Data | Checksum |
| :---: | :---: | :---: | :---: |
| FFh | ID | 00 h | $00 \mathrm{~h}-\mathrm{FFh}$ |

## Move Zoom to Tele

| Synch Byte | Address | Command1 | Command2 | Data1 | Data2 | Checksum |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| FFh | ID | $\mathbf{0 0 h}$ | $\mathbf{2 0 h}$ | $\mathbf{0 0 h}$ | $\mathbf{0 0 h}$ | 00h-FFh |

reply

| Synch Byte | Address | Data | Checksum |
| :---: | :---: | :---: | :---: |
| FFh | ID | 00 h | $00 \mathrm{~h}-\mathrm{FFh}$ |

Stop

| Synch Byte | Address | Command1 | Command2 | Data1 | Data2 | Checksum |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| FFh | ID | $\mathbf{0 0 h}$ | $\mathbf{0 0 h}$ | $\mathbf{0 0 h}$ | $\mathbf{0 0 h}$ | 00h-FFh |

reply

| Synch Byte | Address | Data | Checksum |
| :---: | :---: | :---: | :---: |
| FFh | ID | 00 h | $00 \mathrm{~h}-\mathrm{FFh}$ |

## Execute AF

| Synch Byte | Address | Command1 | Command2 | Data1 | Data2 | Checksum |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| FFh | ID | $\mathbf{0 0 h}$ | 2Bh | $\mathbf{0 0 h}$ | $\mathbf{0 0 h}$ | 00h-FFh |

Duaring performing this command, some commands can be queued in the queueing memory. The queueing memory is 128 bytes. You can set to on/off the queueing in the OSD menu. The auto-focusing could be interrupted to quit by Move Focus commands and Stop command.
reply

| Synch Byte | Address | Data | Checksum |
| :---: | :---: | :---: | :---: |
| FFh | ID | 00 h | $00 \mathrm{~h}-\mathrm{FFh}$ |

## Inquiry Focus position

| Synch Byte Address Command1 Command2 Data1 Data2 Checksum <br> FFh ID $\mathbf{0 0 h}$ $\mathbf{8 B h}$ $\mathbf{0 0 h}$ $\mathbf{0 0 h}$ 00h-FFh <br> reply       <br> Synch Byte Address Command1 Command2 Data1 Data2 <br> FFh ID $\mathbf{0 0 h}$ $\mathbf{8 D h}$ MSB LSB      $>=$ 00h-FFh |
| :--- |

The position is described in Data1 and Data2 as 16bits value(0000h-FFFFh)

## Inquiry Zoom position

| Synch Byte | Address | Command1 | Command2 | Data1 | Data2 | Checksum |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| FFh | ID | $\mathbf{0 0 h}$ | $\mathbf{5 5 h}$ | $\mathbf{0 0 h}$ | $\mathbf{0 0 h}$ | 00h-FFh |

reply

| Synch Byte | Address | Command1 | Command2 | Data1 | Data2 | Checksum |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| FFh | ID | $\mathbf{0 0 h}$ | $\mathbf{5 D h}$ | MSB | LSB | 00h-FFh |

The position is described in Data1 and Data2 as 16bits value(0000h-FFFFh)

## Set Zoom position

| Synch Byte | Address | Command1 | Command2 | Data1 | Data2 | Checksum |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| FFh | ID | $\mathbf{0 0 h}$ | $\mathbf{4 F h}$ | MSB | LSB | 00h-FFh |

The position is described in Data1 and Data2 as 16bits value (0000h-FFFFh). While performing this command, some commands can be queued in the queueing memory. The queueing memory is 128 bytes. You can set to on/off the queueing in the OSD menu.
reply

| Synch Byte | Address | Data | Checksum |
| :---: | :---: | :---: | :---: |
| FFh | ID | 00 h | $00 \mathrm{~h}-\mathrm{FFh}$ |

## Set Focus position

| Synch Byte | Address | Command1 | Command2 | Data1 | Data2 | Checksum |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| FFh | ID | $\mathbf{0 0 h}$ | $\mathbf{8 7 h}$ | MSB | LSB | 00h-FFh |

The position is described in Data1 and Data2 as 16bits value ( $0000 \mathrm{~h}-\mathrm{FFFFh}$ ). While performing this command, some commands can be queued in the queueing memory. The queueing memory is 128 bytes. You can set to on/off the queueing in the OSD menu.
reply

| Synch Byte | Address | Data | Checksum |
| :---: | :---: | :---: | :---: |
| FFh | ID | 00 h | $00 \mathrm{~h}-\mathrm{FFh}$ |


| Synch Byte | Address | Command1 | Command2 | Data1 | Data2 | Checksum |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| FFh | ID | $\mathbf{0 0 h}$ | $\mathbf{8 3 h}$ | kinds | speed | 00h-FFh |

kinds:

| 00 h | SLOWEST SPEED |
| :--- | :--- |
| 01 h | LOW MEDIUM SPEED |
| 02 h | HIGH MEDIUM SPEED |
| 03 h | HIGHEST SPEED |

The speed is described in Data2 as 8 bits valus $(00 \mathrm{~h}-\mathrm{FFh})$
The speed is stored in the non volatile memory in the lens.
reply

| Synch Byte | Address | Data | Checksum |
| :---: | :---: | :---: | :---: |
| FFh | ID | 00 h | $00 \mathrm{~h}-\mathrm{FFh}$ |

## Set Continuously Zoom Speed

| Synch Byte | Address | Command1 | Command2 | Data1 | Data2 | Checksum |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| FFh | ID | $\mathbf{0 0 h}$ | $\mathbf{8 1 h}$ | kinds | speed | 00h-FFh |

kinds:

| 00 h | SLOWEST SPEED |
| :--- | :--- |
| 01 h | LOW MEDIUM SPEED |
| 02 h | HIGH MEDIUM SPEED |
| 03 h | HIGHEST SPEED |

The speed is described in Data2 as 8 bits valus $(00 \mathrm{~h}-\mathrm{FFh})$. The speed is stored in the non volatile memory in the lens.
reply

| Synch Byte | Address | Data | Checksum |
| :---: | :---: | :---: | :---: |
| FFh | ID | 00 h | $00 \mathrm{~h}-\mathrm{FFh}$ |

## Set Focus Speed

| Synch Byte | Address | Command1 | Command2 | Data1 | Data2 | Checksum |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| FFh | ID | $\mathbf{0 0 h}$ | $\mathbf{2 7 h}$ | $\mathbf{0 0 h}$ | kinds | 00h-FFh |

kinds:

| 00 h | SLOWEST SPEED |
| :--- | :--- |
| 01 h | LOW MEDIUM SPEED |
| 02 h | HIGH MEDIUM SPEED |
| 03 h | HIGHEST SPEED |

*The focus speed can be set to one of them.
reply

| Synch Byte | Address | Data | Checksum |
| :---: | :---: | :---: | :---: |
| FFh | ID | 00 h | 00h-FFh |


| Synch Byte | Address | Command1 | Command2 | Data1 | Data2 | Checksum |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| FFh | ID | $\mathbf{0 0 h}$ | $\mathbf{2 5 h}$ | $\mathbf{0 0 h}$ | kinds | 00h-FFh |

kinds:

| 00 h | SLOWEST SPEED |
| :--- | :--- |
| 01 h | LOW MEDIUM SPEED |
| 02 h | HIGH MEDIUM SPEED |
| 03 h | HIGHEST SPEED |

*The zoom speed can be set to one of them.
reply

| Synch Byte | Address | Data | Checksum |
| :---: | :---: | :---: | :---: |
| FFh | ID | 00 h | $00 \mathrm{~h}-\mathrm{FFh}$ |

## Set Preset

| Synch Byte | Address | Command1 | Command2 | Data1 | Data2 | Checksum |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| FFh | ID | $\mathbf{0 0 h}$ | $\mathbf{0 3 h}$ | $\mathbf{0 0 h}$ | preset_id | 00h-FFh |

preset_id is described in Data2 as 8 bits valus $(01 \mathrm{~h}-\mathrm{FFh})$. The lens has 255 zoom and focus position memories. The lens can storage the current zoom and focus positions into the memory.
reply

| Synch Byte | Address | Data | Checksum |
| :---: | :---: | :---: | :---: |
| FFh | ID | 00 h | $00 \mathrm{~h}-\mathrm{FFh}$ |

## Call Preset

| Synch Byte | Address | Command1 | Command2 | Data1 | Data2 | Checksum |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| FFh | ID | $\mathbf{0 0 h}$ | $\mathbf{0 7 h}$ | $\mathbf{0 0 h}$ | preset_id | 00h-FFh |

preset_id is described in Data2 as 8 bits valus( $01 \mathrm{~h}-\mathrm{FFh}$ ). The zoom and focus preset positions is called from the preset memory, and the zoom and focus positions are changed as the preset positions.
reply

| Synch Byte | Address | Data | Checksum |
| :---: | :---: | :---: | :---: |
| FFh | ID | 00 h | $00 \mathrm{~h}-\mathrm{FFh}$ |

## Clear Preset

| Synch Byte | Address | Command1 | Command2 | Data1 | Data2 | Checksum |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| FFh | ID | $\mathbf{0 0 h}$ | $\mathbf{0 5 h}$ | $\mathbf{0 0 h}$ | preset_id | 00h-FFh |

preset_id is described in Data2 as 8 bits valus $(01 \mathrm{~h}-\mathrm{FFh})$. The preset position stored in the memory is cleared.
reply

| Synch Byte | Address | Data | Checksum |
| :---: | :---: | :---: | :---: |
| FFh | ID | 00 h | $00 \mathrm{~h}-$ FFh |

8. OSD menu.

You can change the setting using the buttons on the rear panel. Hold down the button for longer than 3 seconds to display the OSD menu.

| PAGE | Menu | Description | Range | Default | Note |
| :---: | :---: | :---: | :---: | :---: | :---: |
| PAGE1 | MODEL | Lens model |  |  | Do not change. |
|  | UARTDUPLEX | The duplex of UART | HALF/FULL | HALF | Needs to reboot. |
|  | BAUDRATE | The baud rate of UART | $\begin{aligned} & \text { 2400/4800/9600/ } \\ & 19200 / 38400 \end{aligned}$ | 9600 | Needs to reboot. |
|  | MY ID | PELCO-D ID of this lens | 01-FF | 01 |  |
|  | FSPEED0 | Focus motor speed (slowest) | 0-255 | 80 |  |
|  | FSPEED1 | Focus motor speed (slow) | 0-255 | 120 |  |
|  | FSPEED2 | Focus motor speed (high) | 0-255 | 200 |  |
|  | FSPEED3 | Focus motor speed (highest) | 0-255 | 255 |  |
| PAGE2 | ZSPEED0 | Zoom motor speed (slowest) | 0-255 | 50 |  |
|  | ZSPEED1 | Zoom motor speed (slow) | 0-255 | 100 |  |
|  | ZSPEED2 | Zoom motor speed (high) | 0-255 | 200 |  |
|  | ZSPEED3 | Zoom motor speed (highest) | 0-255 | 255 |  |
|  | AMPGAIN | Gain of the focus amplifier | Low/High | High | Do not change |
|  | ZOOM AF | Automatic AF after zoom stopped | ON/OFF | OFF |  |
|  | ZOOMAF DELAY | The delay of ZOOM AF (msec) | 0-10000 | 1000 |  |
|  | PT AF | Automatic AF after Pan-Tilt stopped | ON/OFF | OFF |  |
|  | PTAF DELAY | The delay of PT AF (msec) | 0-10000 | 1000 |  |
| PAGE3 | PT ID | The ID of the Pan-Tilt | 01-FF | 02 |  |
|  | AFAREASIZE | AF area size | S/M/L | M |  |
|  | AFAREAFRAME | AF area display | OFF/RECT/FILL | OFF |  |
|  | MOTOR EXT | External motor control | ON/OFF | OFF |  |
|  | MOTOR PRI | The priority of motor control | EXT/INT | INT |  |
|  | MOTOR FILTER | The filter frequency of external direct motor control | None/100ns/ $1 u / 10 u$ | 10us | Needs to reboot. |
|  | ZOOM POS INV | Inverse of the zoom potentiometer value direction | ON/OFF | OFF | Needs to reboot. |
|  | FOCUS POS INV | Inverse of the focus potentiometer value direction | ON/OFF | OFF | Needs to reboot. |
|  | AF SEARCH | The range of AF searching | FULL/HALF | FULL | Do not change |
| PAGE4 | RS422T PHASE | The phase of RS422 Tx signal | NORMAL/ <br> INVERSE | NORMAL | Needs to reboot. |
|  | RS422R PHASE | The phase of RS422 Rx signal | NORMAL/ <br> INVERSE | NORMAL | Needs to reboot. |
|  | AFDEMO | Test function | ON/OFF | OFF | Do not change |
|  | H FREQ | The frequency of horizontal | - | - |  |


|  |  | synchronization signal |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
|  | V FREQ | The frequency of vertical synchronization signal |  | - |  |
|  | FW VERSION | The Firmware version | - | - |  |
|  | FPGA VERSION | The FPGA version | - | - |  |
| PAGE5 | DEBUG | Test function | ON/OFF | OFF | Do not change |
|  | AF TIMEOUT | AF Timeout | 10-120 | 30 |  |
|  | CMD QING AF | Command queueing while AF performing | ON/OFF | ON |  |
|  | CMD QING PRESET | Command queueing while preset command performing | ON/OFF | ON |  |
|  | PWM FREQ | The frequency of PWM signal for the motor in kHz | 1-100 | 1 |  |
|  | ZOOM LS POS | The position of the software limit switch for Move Zoom Command | 1-1000 | 50 |  |
|  | RESET SETTING | Resetting all setting to the default | OFF/RESET | OFF | Do not change *After reset all setting, MODEL should be configured as collect lens modelname. |

Table 5 OSD menu

## 9. Polarity and Direction

| model | Inquiry Zoom position (Default) | Inquiry Focus position (Default) | $\begin{gathered} \text { FOCUS } \\ \text { CONTROL+/- } \end{gathered}$ | $\begin{gathered} \text { ZOOM } \\ \text { CONTROL+/- } \end{gathered}$ |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| LMZ1236AMPDC-XFAF <br> LMZ0824AMPDC-XFAF | Tele:0x0000 <br> Wide:0xFFFF | Near:0x0000 <br> Far:0xFFFF | Far: Apply +12 V to "CONTROL+" <br> Near: Apply +12 V <br> to "CONTROL-" | Tele: Apply +12 V <br> to "CONTROL+" <br> Wide: Apply +12 V <br> to "CONTROL-" | Far: High(+5V) <br> Near: Low(0V) | Tele: High $(+5 \mathrm{~V})$ Wide: Low(0V) |
| LMZ1000AMPDC-XFAF | Tele:0x0000 <br> Wide:0xFFFF | Near:0x0000 <br> Far:0xFFFF | Far: Apply +12V to " CONTROL-" Near: Apply +12 V to "CONTROL+" | Tele: Apply +12 V <br> to "CONTROL+" <br> Wide: Apply +12 V <br> to "CONTROL-" | Far: Low(0V) <br> Near: High( +5 V ) | Tele: Low(0V) Wide: $\operatorname{High}(+5 \mathrm{~V})$ |
| LMZ20750AMPDC-XFAF <br> LMZ20550AMPDC-IRAF | Tele:0x0000 <br> Wide:0xFFFF | $\begin{aligned} & \text { Near:0x0000 } \\ & \text { Far:0xFFFF } \end{aligned}$ | Far: Apply +12 V to " CONTROL+" Near: Apply +12V to "CONTROL-" | Tele: Apply +12 V <br> to "CONTROL+" <br> Wide: Apply +12 V <br> to "CONTROL-" | Far: High(+5V) Near: Low(0V) | Tele: Low(0V) Wide: $\operatorname{High}(+5 \mathrm{~V})$ |
| LMZ11176AMPDC-IRAF LMZ10360AMPDC-IRAF LMZ14500AMPDC-IRAF LMZ25300AMPDC-IRAF LMZ16160AMPDC-IRAF | Tele:0x0000 <br> Wide:0xFFFF | Near:0x0000 <br> Far:0xFFFF | Far: Apply +12 V to "CONTROL+" Near: Apply +12 V to "CONTROL-" | Tele: Apply +12 V <br> to "CONTROL+" <br> Wide: Apply +12 V <br> to "CONTROL-" | Far: Low(0V) <br> Near: High $(+5 \mathrm{~V})$ | Tele: High $(+5 \mathrm{~V})$ Wide: Low(0V) |
| LMZ375AMPDC-XF with external AF PCB | Tele:0x0000 <br> Wide:0xFFFF | Near:0x0000 <br> Far:0xFFFF | Far: Apply +12V to " CONTROL-" <br> Near: Apply +12 V <br> to "CONTROL+" | Tele: Apply +12 V <br> to "CONTROL+" <br> Wide: Apply +12 V <br> to "CONTROL-" | Far: $\operatorname{High}(+5 \mathrm{~V})$ <br> Near: Low(0V) | Tele: High $(+5 \mathrm{~V})$ <br> Wide: Low(0V) |

## 10. Disclaimer

- KOWA OPTICAL PRODUCTS CO., LTD. shall not be liable for any failure, physical damage, or loss caused by a fire, an earthquake, flood damage, lightening, a conduct of a third party, any other accident, your intentional or unintentional improper handling and/or use of the product, or any other abnormal use condition (even if it is ascribable to a third party).
- KOWA OPTICAL PRODUCTS CO., LTD. shall not be liable for any loss (including a loss of operating profits, a loss due to business interruption, and changes to a loss of stored data) caused by the use of the product or inability to use the product.
- KOWA OPTICAL PRODUCTS CO., LTD. shall not be liable for any loss caused by failure to follow any instruction in this instruction manual.
- KOWA OPTICAL PRODUCTS CO., LTD. shall not be liable for any loss caused by a malfunction ascribable to any device connected with the product.
- The warranty period for the product shall be one year from the delivery date.
- Do not disassemble or alter the product. Doing so voids the warranty even if one year has not passed since the delivery date.
- KOWA OPTICAL PRODUCTS CO., LTD. shall not be liable for any failure or physical damage caused by the maintenance or repair not performed by KOWA OPTICAL PRODUCTS CO., LTD. or the distributer from which you purchased the product.
- Even after the warranty period, KOWA OPTICAL PRODUCTS CO., LTD. will repair the product at cost upon your request if the repair enables the product to maintain its intended functions.
- KOWA OPTICAL PRODUCTS CO., LTD. shall not warrant the product against any problem caused by a factor not mentioned in this instruction manual and therefore shall not be liable for it.


## 11. Federal Communications Commission

This device complies with part 15 of the FCC Rules. Operation is subject to the following two conditions: (1) This device may not cause harmful interference, and (2) this device must accept any interference received, including interference that may cause undesired operation.
Note: This equipment has been tested and found to comply with the limits for a Class A digital device, pursuant to part 15 of the FCC Rules. These limits are designed to provide reasonable protection against harmful interference when the equipment is operated in a commercial environment. This equipment generates, uses, and can radiate radio frequency energy and, if not installed and used in accordance with the instruction manual, may cause harmful interference to radio communications.
Operation of this equipment in a residential area is likely to cause harmful interference in which case the user will be required to correct the interference at his own expense.

